Philippe Moustrou, UiT - The Arctic University of NorwayJoint work with M. Dostert (KTH) and D. de Laat (TU Delft).Combinatorics and Geometric Days III - December 4, 2020

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Problem:

Usually semidefinite programming provides approximate numerical bounds.

How can we turn these bounds into exact bounds?

How many unit spheres can simultaneously touch a central unit sphere without overlapping?

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Known in dimensions 1, 2, 3 (Schutte, vander Waerden, 1953),4 (Musin, 2008), 8 and 24 (Levenshtein / Odlyzko, Sloane, 1979).

#### Formulation and generalizations



Kissing number:

 $\max\{|C|, \quad C \subset S^{n-1}, \quad x \cdot y \le 1/2 \text{ for all } x \neq y \in C\}$ 

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Spherical codes:

 $\max\{|C|, \quad C \subset S^{n-1}, \quad x \cdot y \leq \cos\theta \text{ for all } x \neq y \in C\}$ 

#### Formulation and generalizations



One-sided kissing number (Musin, 2006):

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• [Dostert, De Laat, M., 2020]: A general framework to prove optimality and uniqueness of such configurations.

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Our problems boil down to computing the independence number of these graphs!

• Lower bounds: Constructions.

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  - For finite graphs: hierarchies of semidefinite upper bounds. (Lovász-Schrijver 1991, Lasserre 2001, Laurent 2007)

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- Upper bounds:
  - For finite graphs: hierarchies of semidefinite upper bounds. (Lovász-Schrijver 1991, Lasserre 2001, Laurent 2007)
  - For infinite graphs: Generalization of Lasserre's hierarchy (de Laat-Vallentin 2015), related to the previous 2-point (Delsarte-Goethals-Seidel 1977) and 3-point bounds (Bachoc-Vallentin 2008).

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, with  $\begin{cases} u = 1 & x = y \\ u \in [-1, \cos \theta] & x \neq y \end{cases}$ 

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• The normalized Gegenbauer polynomials  $P_k^n(u)$  (with  $P_k^n(1) = 1$ ), satisfying:

For every 
$$X \subset S^{n-1}$$
 finite,  $\sum_{x,y \in X} P_k^n(x \cdot y) \ge 0$ .

Assume we have a polynomial f such that

• there exists coefficients  $\alpha_0, \ldots, \alpha_d \geq 0$  such that

$$f(u) = \sum_{k=0}^{d} \alpha_k P_k^n(u).$$

•  $f(u) \leq -1$  for all  $u \in [-1, \cos \theta]$ 

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#### 2-point bound for spherical codes (Delsarte-Goethals-Seidel 1977)

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Then, if C is a  $\theta$ -spherical code,

$$0 \le \sum_{k=0}^{d} \alpha_k (\sum_{x,y \in C} P_k^n(x \cdot y)) = \sum_{x,y \in C} f(x \cdot y) \le |C|f(1) + \sum_{x \ne y} f(x \cdot y) = |C|(f(1) - |C| + 1)$$
  
So

 $|C| \leq f(1) + 1$ 

So for every  $d \ge 0$ , the size of a  $\theta$ -spherical code is at most

$$\begin{split} \min\{M \in \mathbb{R} : \alpha_0, \dots, \alpha_d \geq 0, \\ f(1) \leq M - 1, \\ f(u) \leq -1 \text{ for all } u \in [-1, \cos \theta]\} \end{split}$$

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So for every  $d \ge 0$ , the size of a  $\theta$ -spherical code is at most

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This is a linear programming bound.

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 Up to symmetry, a triple of points x, y, z in a θ-spherical code is uniquely determined by

$$u = x \cdot y, \quad v = x \cdot z, \quad t = y \cdot z,$$

with (u, v, t) in

$$\begin{cases} \{(1,1,1)\} & x = y = z \\ \Delta_0 = \{(u,u,1) : u \in [-1,\cos\theta]\} & x \neq y = z \\ \Delta & x, y, z \text{ distinct} \end{cases}$$

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$$\Delta = \{(u, v, t) : u, v, t \in [-1, \cos \theta], 1 + 2uvt - u^2 - v^2 - t^2 \ge 0\}$$

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• Matrix polynomials  $S_k^n(u, v, t)$  satisfying:

For every 
$$X \subset S^{n-1}$$
 finite,  $\sum_{x,y,z \in X} S_k^n(x \cdot y, x \cdot z, y \cdot t) \succeq 0.$  10

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\begin{split} \min\{M \in \mathbb{R} : \alpha_k \ge 0, F_k \succeq 0\\ \sum_{k=0}^d \alpha_k + F(1, 1, 1) \le M - 1,\\ \sum_{k=0}^d \alpha_k P_k^n(u) + 3F(u, u, 1) \le -1 \text{ for all } u \in [-1, \cos \theta],\\ F(u, v, t) \le 0 \text{ for all } (u, v, t) \in \Delta\} \end{split}
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min

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This leads to semidefinite upper bounds using sums of squares.

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- Optimization: When does a bound give the independence number?
- Geometry: Sharp bounds provide additional information on optimal configurations, leading to uniqueness proofs.



- For spherical codes, including kissing number:
  - 2-point bound  $\rightarrow$  linear programming bound
  - 3-point bound  $\rightarrow$  semidefinite programming bound



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- For spherical codes in spherical caps, like hemisphere:
  - Delsarte bound does not apply anymore due to the lack of symmetry.
  - The 3-point bound can be adapted to a 2-point semidefinite programming bound (Bachoc-Vallentin 2009).

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- Numerically sharp for the square antiprism (Bachoc-Vallentin 2009)  $\rightarrow$  Rigorous proof (Dostert-de Laat-M 2020)
- *E*<sub>8</sub> gives an optimal configuration on the hemisphere in dimension 8 (Bachoc-Vallentin 2009)
  - $\rightarrow$  Uniqueness (Dostert-de Laat-M 2020)

A semidefinite program:



with x the vector of unknowns, and  $\mathcal{B}_i(x)$  the blocks of x.

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$$\inf\{\underbrace{c^{t}x}_{\text{objective}} : \underbrace{Ax = b}_{\text{linear constraints}}, \underbrace{\mathcal{B}_{i}(x) \succeq 0}_{\text{PSD constraints}}\}$$

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- Our context: The problems provide a candidate field to round over, either Q or Q(√d).

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The linear system is then satisfied... But what about the PSD conditions?
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- Sometimes, zero eigenvalues can be forced by some additional affine constraints coming from an optimal configuration. This is sometimes enough... (Cohn-Woo 2012).
- Sometimes not. By undertsanding the kernels, we can force all these constraints!

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Thank you!